

All-Axis
Servo Driven
Type

Swing Type

Side Entry
Type

For Vertical
Molding
Machine

Stock System

Product
Series
Guide [P11]

N-HOP-G II 450/550/650/750/900-R1

Servo motor-driven kick axis adopted to support frequent changeovers



Clamping force 30 - 350 tf

Servo + Air-driven

Runner Take-Out Robot with Servo Motor-Driven Kick Axis

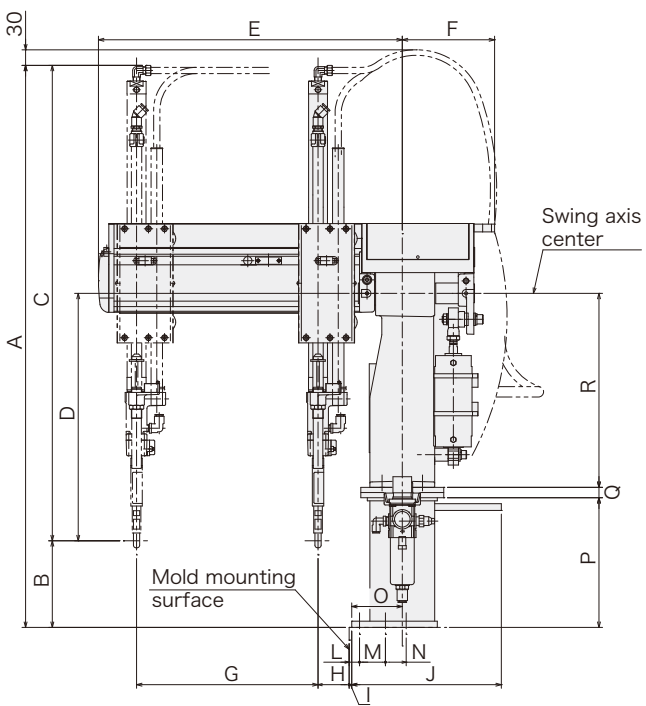
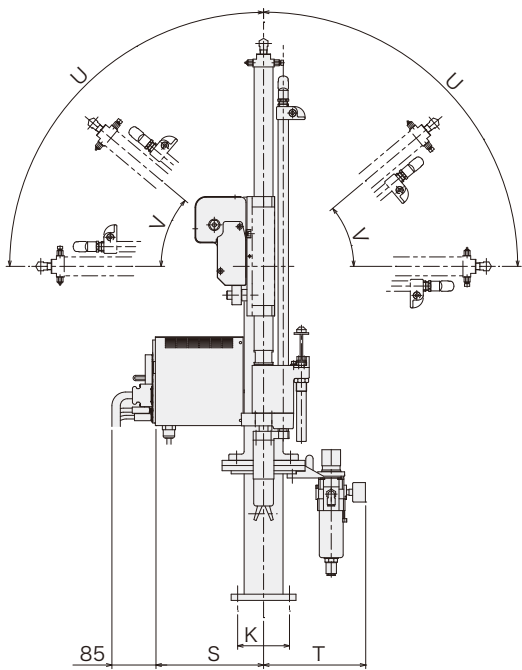
In a swing type robot,the item that requires the most frequent adjustment in connection with mold changes is the kick stroke. The kick axis of the N-HOP is driven with a numerically controlled servomotor,which allows the adjustment to be executed safely and accurately without climbing on top of the molding machine.The servomotor also provides a fast and stable runner take-out motion that can only be achieved with servo-motor drive.

Standard Specifications

Power supply		Drive method		Controller model		Working air pressure		
1-phase 200 VAC/220 VAC (50/60 Hz)		Digital servo motor (1-axis) Air cylinder (2-axis)		GII B-type controller		0.49 MPa		
Model	Power consumption	Stroke			Chuck position [mm]	Air consumption [NL/cycle]	Payload [kg]	Target IMM clamp capacity [tf]
		Vertical[mm]	Kick[mm]	Swing				
N-HOP-GII 450-R1	0.13 kVA 200 VAC 0.7 A	450	350	Min.50° Max.90°	Range 100	11	2	30-350
N-HOP-GII 550-R1		550				13		
N-HOP-GII 650-R1		650				15		
N-HOP-GII 750-R1		750	17					
N-HOP-GII 900-R1		900	620			19		

X, XC, and XN Specifications are available.
Payload includes the end-of-arm tool.

Dimensional Drawings [mm]



Separate catalog available

[mm]

Model	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V
N-HOP-GII 450-R1	1084		917																			
N-HOP-GII 550-R1	1184	167	1017		586		350		5	289	100	20	50	40	98	250				197		
N-HOP-GII 650-R1	1284		1117	477		178		60									20	374	208		90°	40°
N-HOP-GII 750-R1	1484		1217																			
N-HOP-GII 900-R1	1634	267	1367		856		620		4	400	128	25	60	60	99	350				222		

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