

1 All-Axis Servo Driven Type Take-Out Robot

CT2-100S/D, CT2-150S/D, CT2-250S/D

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Introducing a new concept that reforms work floor layouts
Compact models for low-clearance installations



Clamping force 80 - 300 tf

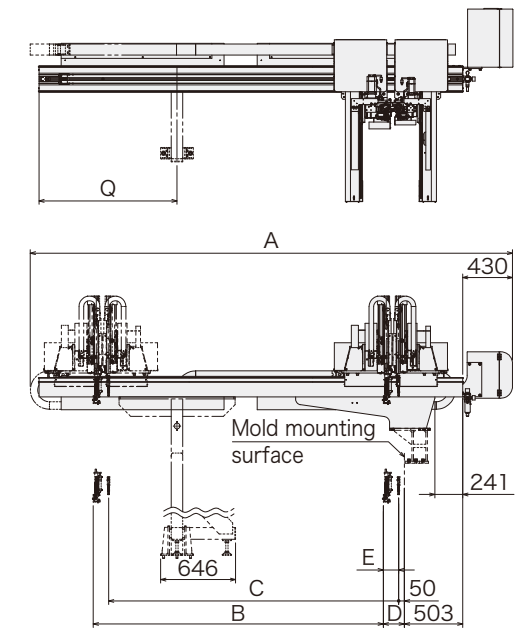
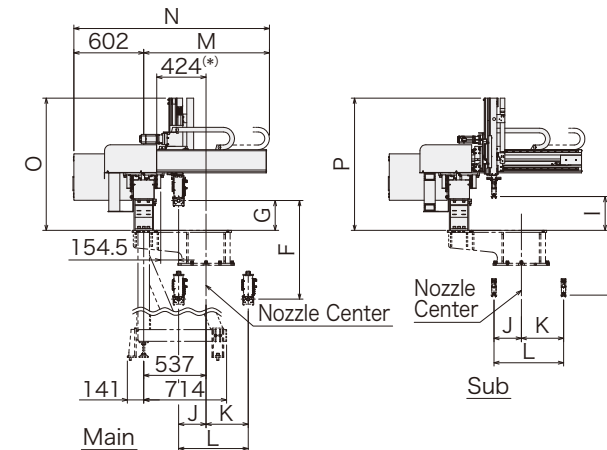
Vibration control

Optimized design + Power-saving

Low posture (Double speed mechanism)

All-axis servo-driven

External Dimensions [mm]



Q : Stanchion should be equipped within 1500 mm from the end of traverse stroke.
(*) "Clearance for mold-changing, from injection-center to rear-side"
To avoid mechanical interference, please be sure to keep the edge of lifted mold within the shown length from the nozzle-center.

Space Efficient

CT robots require less clearance between molding machines, which helps fit more units on the production floor.

Switching from Runner Take-out to Product Take-out

Replace your existing runner take-out robot with a new product take-out robot—no additional space needed.

Centralization of Conveyor Belts

No need to have a conveyor belt for each molding machine—this series enables centralized inspection and packing with just one conveyor belt.

Equipped with E-touch compact-YC as standard



- ECO Vacuum™
- ECO Monitor™
- Predictive Maintenance*

* Continuously monitors take-out robot during operation and alerts operator with a message if any signs of potential trouble are detected.

Standard Specifications

Power supply		Drive method		Controller model		Working air pressure		Flip angle		
1-phase 200 VAC/220 VAC/230 VAC (50/60 Hz)		Digital servo motor 3/6-axis		E-touch compact-YC		0.49 MPa		90°		
Model	Power consumption	Clamp-end traverse stroke [mm]		Traverse stroke [mm]		Vertical stroke [mm]		Air consumption [NL/cycle]	Payload [kg]	Target IMM clamp capacity [tf]
		Main arm	Sub arm	Main arm	Sub arm	Main arm	Sub arm			
CT2-100S	S type 1.9 kVA 200 VAC 9.3 A	S type 2560 (3060) (3560) (4060) (4560)	—	600	—	700	—	7.3 ECO Vacuum OFF 2.0 ECO Vacuum ON	5	80-130
CT2-100D		2500 (3000) (3500) (4000) (4500)	600		700					
CT2-150S		D type 2.9 kVA 200 VAC 14.3 A	—		—	600	850 (950)			—
CT2-150D	D type 2500 (3000) (3500) (4000) (4500)		600	850 (950)						
CT2-250S	—		—	—	750	950 (1100)	—	8.0 ECO Vacuum OFF 2.4 ECO Vacuum ON	180-300	
CT2-250D		2500 (3000) (3500) (4000) (4500)	750	950 (1100)						

S type : Robot is equipped with main arm only. D type : Robot is equipped with main arm and sub arm. () : Modified stroke. Payload includes the end-of-arm tool.
Stanchion is standard equipment regardless of the clamp traverse stroke length.

() : Modified stroke

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