

# Power Setup

## 로봇 전원 세팅

1. Attach the hoist to the lifting rings located on the robot's shoulders.
2. Lift the robot out of the packaging box using the hoist.
3. Press the white power button on the rear of the robot to turn it on.

# Controller Pairing

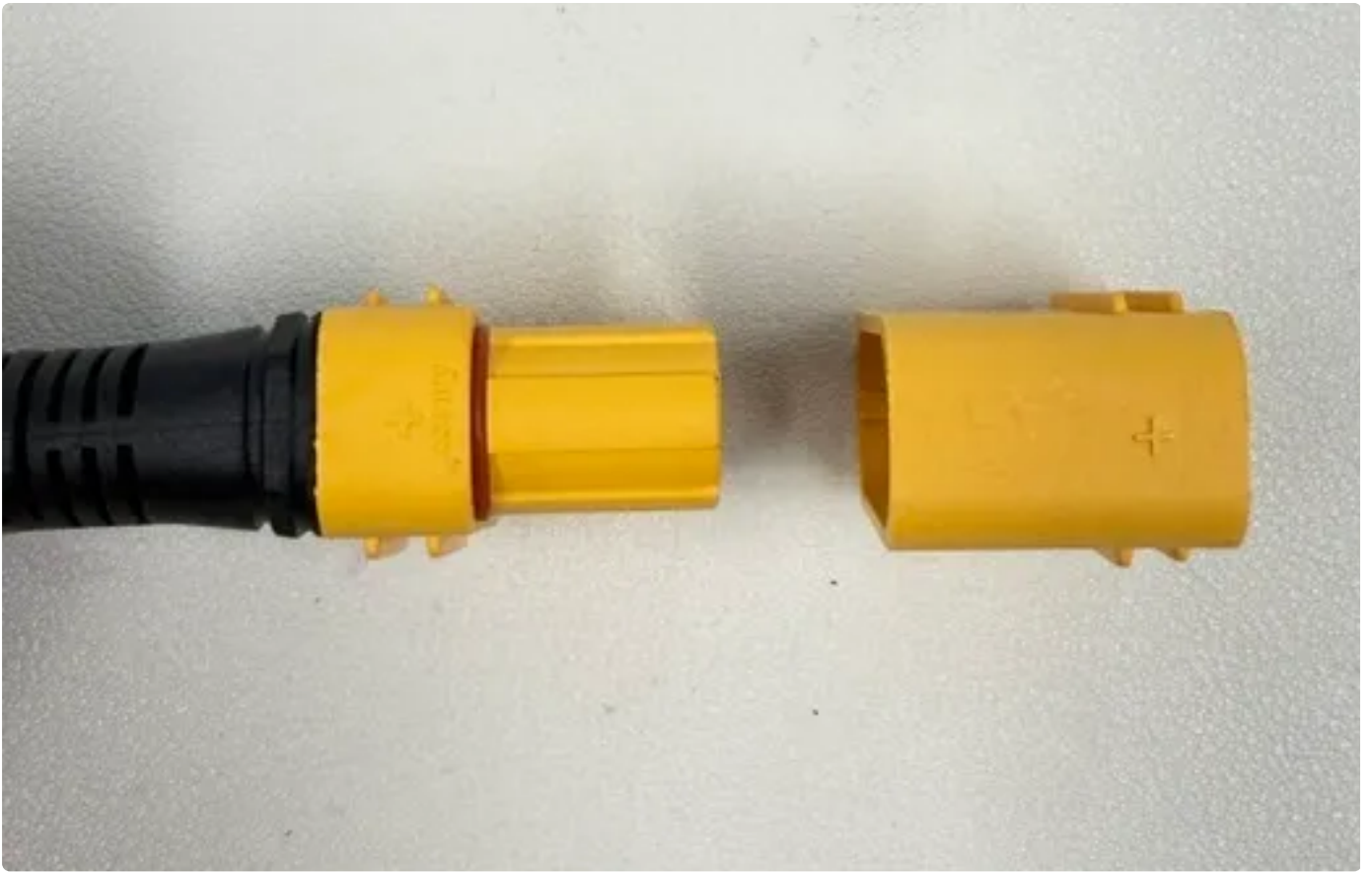
## 로봇 - 앱 컨트롤러 페어링

1. Launch the App Controller.
2. Select the robot you wish to connect to, complete BLE authentication, and choose a connection mode.
3. If using AP Mode, connect to the robot's access point (AP), configure the same Wi-Fi network, and establish the connection.
4. From the app's main screen, enter **Control Mode**.
5. Follow the on-screen instructions to complete the required step-by-step sequence for entering Control Mode.
6. If a robotic hand is installed, perform **Hand Initialization** before operation.

# Battery Installation

## 배터리 장착

1. Inspect the battery for any signs of external damage.
2. Check the battery compartment for damage, sharp edges, or interference from internal wiring. Ensure the compartment is clear so the battery can be inserted safely.
3. Insert the battery fully into the compartment with the battery terminals facing to the **right**, matching the orientation of the slot. Lock both retaining latches. (Rotate each latch **90° counterclockwise** from the horizontal position. The latch is fully locked when it is in the **vertical** position.)
4. Pull the battery handle gently to confirm that the battery is securely locked in place, then fold the handle upward.
5. Verify the polarity of the battery connector and power cable (+ and -), and connect them in the correct orientation. (See the figure below.)



## 6. Installing the Battery Cover

- Insert the lower tabs of the cover into the slots at the bottom of the battery compartment.
- Press both sides of the cover until the retaining clips engage securely.

## 7. Press the **white power button** on the rear of the robot to turn it on.